

A Tolerance Management Domain Model (ToleranceDM) for Semantic Enrichment of BIMs

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Abstract: Dimensional variability of components and assemblies in construction can lead to significant defects, rework, and project risk if not managed effectively. Given the complexity of using tolerance management to control dimensional variability, an automated BIM-based approach is highly propitious, while currently elusive. This paper develops the first iteration of a domain model for tolerance management (ToleranceDM) using two case study examples within the domain of building construction. The results are shown to (1) consolidate the scattered, disparate existing "knowledge" and research on tolerance management into a single standardised, uniform framework, and (2) formalise this knowledge so that it can be unambiguously interpreted and parsed into software systems for automated tolerance management in construction. ToleranceDM functions as a key step towards benchmarking process capabilities, computing tolerance compliance automatically, and enabling in-field communication of tolerance requirements. Future research should explore case studies in different construction domains, along with developing an improved abduction framework and integrating as-built project data for tolerance compliance checking.

Keywords: domain model, dependency structure matrix, tolerance management, building information model, tolerance analysis, risk management

1.0 Introduction

The impacts of dimensional variability are well documented in literature, yet continue to be a source of rework, cost-overruns, delays, and litigation on construction projects. Frequent examples reveal how poor project performance can be directly tied to improper consideration and control of dimensional variability [1-4]. In severe cases, these impacts can completely halt projects and be the single largest contributor to cost and time overruns [5]. Tolerance management has emerged within the construction industry as a dependable practice for ensuring dimensional variability is controlled within allowable limits [6-8]. State-of-the-art for tolerance management in construction is still manual and tedious, eliciting an extensive understanding of theory that is perceived as difficult to implement in practice [9]. As a result, it can sometimes be deemed more cost-effective to not allocate any resources or consideration for proper tolerance management and opt to solve dimensional conflicts reactively in-situ as and when they occur [10]. However, this can significantly increase a project's risk exposure [11].

Tolerance management is focused on employing a set of methods [12] to (1) minimise defects associated with dimensional and geometric variability (called tolerance issues hereafter) in a prescient manner [11,13],

42 and (2) to ensure constructability of components and assemblies [3]. The ultimate aim of tolerance
43 management is to minimise resources spent to modify tolerance issues and ensure structural safety,
44 constructability, aesthetics, and functionality of buildings. These can only be achieved if more judicious
45 decisions are made upstream in the process rather than downstream once construction activities have
46 commenced [6]. Despite its potential value, tolerance management is currently beset by taxing manual
47 activities, which are not conducive for use on most construction projects.

48 Automated tolerance management has the potential to reduce barriers for application in practice, can be
49 applied proactively, and builds the foundation for advanced tolerance optimisation methods. Motivation for
50 automated tolerance management is evident when considering the requirements of emerging technologies
51 and processes in construction. The proliferation of a fully autonomous or robotic construction site requires
52 codified design rules and assembly processes that cannot be based on manual methods for resolving
53 dimensional variability conflicts (i.e., trial and error or rules of thumb practices) [14]. For instance, large-
54 scale additive manufacturing is highly time-sensitive and the final geometry is based on complex design
55 and process parameters [15]. For such processes, researchers have recently demonstrated the efficacy of
56 applying tolerance management principles for characterizing, analysing and controlling the adverse effects
57 of dimensional variability in a prescient manner [16]. Saidi et al. [17] also argue that the state of robotics
58 in construction faces an uphill battle due, in part, to the absence of proper tolerance management. Given
59 the necessity for robotic systems to rely on and employ digital information, an automated tolerance
60 management system is essential for further advancing the state of automation in construction.

61 In order to deploy automated tolerance management in construction, it is first necessary to have semantic
62 information enriched within a Building Information Model (BIM) that contains necessary information about
63 tolerances. Since a generalisable process for such semantic enrichment is currently elusive, this paper
64 presents a novel tolerance domain model (i.e., a structured collection of tolerance concepts and relationships
65 between those concepts, similar to the notion of a "schema", or ontology) for use in construction. This
66 model, herein referred to as ToleranceDM, collects, classifies, and evaluates information from the academic
67 literature, codes of practice, design standards (specifically for steel and concrete), and expert knowledge.

68 The basic function of ToleranceDM is to take an initial BIM and to enrich relevant tolerance information
69 into it using pre-defined rules, a design structure matrix for describing connection points and an inference
70 engine for integrating risk. In doing so, ToleranceDM addresses three prevailing challenges facing
71 automated tolerance management in construction. First, it serves as a centralized mechanism for collecting
72 disparate tolerance management knowledge (such generated knowledge is currently siloed across projects).
73 Second, it functions as a generalizable framework that can be applied across a broad range of construction
74 projects. Third, it explores the required Level of Development (LOD) in a BIM for initiating various
75 tolerance management tasks (e.g., tolerance analysis). LOD is a specification schema that prescribes
76 generally agreed-upon levels of development of a BIM. It is intended to be used to improve the
77 communication of 3D information contained within a BIM. Within the context of prescribing tolerances,
78 the building information modelling LOD is particularly important since each LOD (i.e., there are six general
79 levels: LOD 100, LOD 200, LOD 300, LOD 350, LOD 400, and LOD 500) prescribes distinct subtleties in
80 terms of object features, geometric envelope accuracy, internal sub-components, and connection detail
81 fidelity [18]. For clarity, this paper refers to the LOD specification framework developed by BIMForum
82 [19], which is initially based on the schema developed by the American Institute of Architects.

83 The presented approach of ToleranceDM in this paper is shown to scale to real-world, large-scale BIMs. In
84 addition, the range of query features in ToleranceDM provide new critical information about tolerance
85 sensitivity between specific components that supports construction planning. The direct beneficiaries for
86 ToleranceDM will be practitioners whose work centres on the modelling of assembly connections,

87 simulation of construction sequencing, and risk managers who need to make informed decisions about
88 product and process design in construction. Once operational, ToleranceDM will also serve as the
89 foundation for automated tolerance management, unlocking new frontiers for autonomous and robotic
90 construction processes.

91 This paper is structured as follows. Section 2 provides background information on the current state of
92 tolerance management in construction. Section 3 provides the methodology used for developing
93 ToleranceDM. Section 4 details the step-by-step implementation of this methodology and Section 5 carries
94 out a functional demonstration on two projects (a small simple structure and a large, complex commercial
95 building). Finally, Section 6 provides conclusions and next steps for research.

96 **2.0 Background**

97 Ontologies used to describe concepts in tolerance management in construction can be verbose; stemming
98 largely from the dense body of knowledge used for product tolerancing in manufacturing, and from separate
99 attempts in recent decades to apply it to construction [5-7,12]. For clarity, this paper presents a condensed
100 overview of tolerance management, along with key definitions, which are elaborated upon in the following
101 sections.

102 **2.1 Related Work on Tolerance Ontologies in Mechanical Product Design**

103 Numerous research efforts have developed ontological approaches for representing and reasoning about
104 tolerances in the field of mechanical product design. What has not been undertaken, to the best of our
105 knowledge, is an ontological account of tolerances in the context of construction. It is useful and important
106 to draw analogies between the two domains in an effort to reuse and adapt knowledge capture approaches,
107 although the kinds of knowledge, the impacts of tolerance, and how tolerance information can be used for
108 decision support is significantly different.

109 Most ontology-based approaches in product design are used (at various design stages) for partially or fully
110 specifying tolerances, allocating numerical tolerance values (e.g., [20-23]), and for facilitating
111 interoperability between design tools (e.g., [24,25]). In [21] the authors use case-based reasoning to
112 automate the specification of tolerances to mechanical parts in a design, and to automatically allocate
113 (numerical) tolerance values. In [22] the authors use ontological reasoning to automatically specify
114 tolerances to parts on a mechanical design at a very early design stage – notably even before geometric
115 details have been committed to.

116 In mechanical assembly design, considerable attention is given to the variety of prototype shapes that
117 products take (e.g., surfaces being spherical, cylindrical, planar, helical, revolute, prismatic) and the
118 implications in terms of positional tolerances, how surfaces can have contact, etc. [20]. In construction,
119 there is far less variety in the shape categories of products, and less variety in the ways that typical products
120 have contact. Indeed, for most of the operational lifetime of various products, two products having "contact"
121 does not directly imply physical contact, as products bend, expand, contract, and stretch. Simply knowing
122 that the positioning of two products is highly sensitive can greatly assist during the construction of a
123 building, i.e., special care can then be taken to ensure the proper placement of the two products, as specific
124 kinds of deviation may have costly ramifications at a later stage in construction.

125 **2.2 Variations and Tolerances**

126 Components in construction are specified with geometric dimensions and key material properties. While
127 nominal dimensions are communicated during design, when components and assemblies are constructed,
128 dimensions cannot be achieved with 100% accuracy. The discrepancy or deviation between the nominal

129 and actual dimension is defined as a dimensional variation [26,27]. The acceptable amount of this variability
130 is defined as the tolerance of a geometric entity (e.g., width, length, height, etc.) or installed position of a
131 component [8,28,29]. In some cases, a distinction is made between a dimensional tolerance (limit placed
132 on size), and geometric tolerance (limit placed on form such as straightness or waviness). Within product
133 tolerancing, variations and tolerances are distinguished between features of an object (e.g., surface, edge,
134 or profile), or the relationship between objects within an assembly. For clarity, this paper consolidates these
135 aspects of tolerance management as intra-object tolerances (i.e., within or related to one object) and inter-
136 object tolerances (i.e., between or related to multiple objects in an assembly). These two aspects are known
137 as tolerance sensitive relations hereafter.

138 Dimensional and geometric variability is the result of many interacting factors; material-related and
139 process-related [30-32]. During design, it is important to ensure that components are properly “toleranced”,
140 such that when aggregated, they can fit together properly. The design must also account for the unique types
141 of construction methods employed (e.g., variations range from less than a millimetre for many factory-
142 made components to several centimetres for many in-situ components) [8,33]. The physical aggregation
143 process also induces geometric variations since gravity loads of the building gradually increase during the
144 construction process, potentially resulting in building settlement, movement, and deformation [34].

145 **2.3 Risks Associated with Dimensional and Geometric Variations**

146 In light of the intricacies of dimensional and geometric variability, Talebi et al. [35] suggest that effective
147 tolerance management should manage key risks that occur in connections comprising two or more
148 components. Rausch et al. [36] summarize these key risks as being related to structural safety,
149 constructability, aesthetics, and functionality.

150 *Structural safety risk* relates to dimensional variations that change the load resistance or stability of a
151 structure and examples include column eccentricity, misaligned connections, and mispositioned rebar.
152 *Constructability risk* relates to the dimensional variations which affect the aggregation quality between
153 mating parts and assemblies. At the part level, there are two extreme cases of poor constructability resulting
154 from dimensional variability: (1) a part is too large to connect into its intended interface(s), and (2) a part
155 is too small to connect properly into its intended interface(s). *Aesthetics risk* relates to dimensional
156 variations that impact the perceived quality of a completed assembly, and often occurs from visible
157 misalignments between connecting parts and components. Finally, *functionality risk* relates to dimensional
158 variations that impact the intended performance or serviceability of an assembly. This is best observed in
159 structural design, where a strict limit is placed on floor deflections. While certain deflections may not
160 negatively impact the structural integrity of a floor, serviceability limit states ensure that occupants do not
161 feel unsafe.

162 **2.4 State of Tolerance Management in Construction**

163 The state of tolerance management has been traditionally beset by reactive practices. In recent years
164 however, several proactive methods have been developed. Penalty-incentive schemes across trades and
165 optimal arrangement of interchangeable components can reduce tolerance-based risk [2]. Such schemes
166 provide limited efficacy however, since systemic interaction of geometry between components cannot
167 purely be solved during production and aggregation of components. A more efficacious approach is needed
168 to perform mitigation during design and to subsequently communicate tolerances effectively. Several
169 comprehensive design approaches have been previously proposed including strict-vs-loose tolerance
170 allocation strategies, kinematic chain-based dimensional variation analysis and Monte Carlo simulation
171 [10,13,37]. Other studies [6,9,28] have attempted to develop processes by which tolerance management
172 methods can be applied in a consolidated and systematic manner. For example, Talebi [12] proposed the

173 Tolerance Management System (TMS) by which already developed methods are divided into five
174 categories, namely identification of tolerance requirements and risks, planning the achievement of tolerance
175 requirements and risks, communication of tolerance information, tolerance compliance method, and
176 learning and documentation. In TMS, the identification of critical connections is of prime importance.
177 However, this approach lacks the implementation in the real world to evaluate its practicality. Also, its full
178 implementation is onerous without automation as it contains many manual tasks.

179 Unfortunately, effective tolerance management is still elusive in many spheres of construction due to the
180 practical barriers facing implementation of existing methods. Often, solutions predicated on manual
181 processes are developed for very specific project demands. As such, there is a need for a holistic process
182 that can be universally applied and that does not warrant extensive background knowledge as required in
183 existing approaches. This is particularly where the use of BIM can afford such a process to be both holistic
184 (as the use of BIM becomes ubiquitous in construction) and automated (as emerging technologies are
185 increasingly digitized). Tolerance management is most effective when applied proactively during the design
186 stage. This paper exploits such an approach using a domain model that can be universally applied and in a
187 highly automated manner.

188 **3.0 Methodology for developing the Tolerance Management Domain Model (ToleranceDM)**

189 This research study develops a domain model (DM) for tolerance management. The IDEF5 methodology
190 for knowledge engineering and ontology development [38] is used for the development of the ToleranceDM
191 in this research study. It is emphasized that while IDEF5 knowledge capture *development process* is
192 adopted, EXPRESS is used as the data model specification language in line with industry standards such as
193 the Industry Foundation Classes. IDEF5 is organized into five stages of domain model development: (1)
194 organization and scoping, (2) data collection, (3) data analysis, (4) initial domain model development, and
195 (5) refinement and validation. The following subsections elaborate on how these stages have been
196 undertaken.

197 **3.1 Organization and Scoping**

198 In this study, the scope of the DM is specifically directed towards new building construction projects, as
199 demonstrated by the presented case study. However, ToleranceDM is general in nature and has the potential
200 to be readily adapted to any kind of construction project. The long-term agenda of this work is the
201 development of a meta-model that captures a more abstract structure of tolerance concepts that are common
202 across a broader scope of construction domains (e.g., bridges, tunnels, geotechnical fields, etc.). The core
203 pre-requisite for implementing this method is an initial BIM with sufficient LOD at key connection points
204 between components, where tolerance relations are prone to certain types of project risk (e.g., structural
205 safety, constructability, etc.). As such, ToleranceDM is agnostic to aggregation between strictly new
206 construction or between new and in-situ construction (e.g., prefabricated components being used in a
207 building renovation/adaptation project – such projects are often prone to tolerance issues due to varying
208 levels of dimensional variability which must be suitably mediated). For the purpose of demonstrating the
209 initial architecture of ToleranceDM however, this paper focuses specifically on new building construction
210 projects.

211 **3.2 Data Collection**

212 The authors of this paper have collectively undertaken seven case studies (previously), in which manifold
213 types of tolerance issues were encountered for the following projects: an industrial pipe rack assembly [13],
214 two 805 m² modular data centres [36], a small-scale steel bridge [39], a 7,500 m² commercial building [40],
215 a 2.3 ha terraced warehouse [40], and a prefabricated accessory dwelling unit [41]. These case studies
216 provide valuable tolerance management related information pertaining to a mixed set of project delivery
217

218 methods (i.e., prefabricated versus in-situ), assembly size, complexity, location, and typology (i.e.,
219 commercial, industrial, residential, infrastructure). The tolerance issues identified in these case studies also
220 represent a broad range of defects associated with dimensional variability, including misalignment between
221 structural components, aesthetically unacceptable gaps between structural and non-structural components,
222 and lack of fit in structural frames.

223 Data for developing ToleranceDM is based on these previous case studies, as well as information extracted
224 from other existing journal articles for tolerance management in construction [3,6,9]. As such,
225 ToleranceDM is built upon existing literature that covers concepts from four domains, namely: architecture,
226 engineering, manufacturing, and construction project management. The purpose of the literature review
227 was to identify the underlying concepts and principles of tolerance management, and to identify the relevant
228 state-of-the-art solutions to automate tolerance management.

229 Tolerance issues identified in the case studies were categorised based on three areas with high tolerance
230 risks, namely (a) the connection between the building structure and the building envelope, (b) the
231 connection between the building structure and internal components, and (c) where stringent tolerances
232 should be specified in the internal area of the building, as suggested by (REF). This categorisation helped
233 authors gain a better understanding of type of tolerance issues in each specific area. Afterwards, the
234 identified solutions in the literature were divided into four areas: (a) identification of tolerance
235 requirements/risks, (b) planning the achievement of tolerance requirements/mitigating tolerance risks, (c)
236 communication of tolerance information, and (d) tolerance compliance control, as proposed by (REF). In
237 this paper, solutions addressing identifying tolerance requirements/risks as well as communication of
238 tolerance information were considered when developing ToleranceDM.

239 **3.3 Data Analysis**

240 After collecting initial information regarding tolerance management, the authors began to analyse and
241 structure the core principles into a cohesive framework. Two types of criteria proposed by Talebi et al. [42]
242 and Hong and Chang [43] were initially found to categorise the overall framework developed in this
243 research. The terminologies needed to create the framework were categorised based on the concepts of
244 *Geometric Dimensioning and Tolerancing (GD&T)* and the tolerance risks proposed by Rausch et al. [36].
245 GD&T is a symbolic ontology [29] that communicates permitted deviations in form, size, orientation, and
246 location of features (e.g., size or surface) for a component [44]. GD&T is also used to define relationships
247 between components within an overall product (i.e., assembly), and has become the de-facto ontology for
248 dimensional specification within the manufacturing industry [45]. The application of GD&T in construction
249 has been recently demonstrated by Talebi et al. [46], which consists of a condensed set of principles more
250 suited to construction processes.

251 While analysing data for the proposed framework, three industry experts on tolerance management were
252 consulted with using a set of semi-structured interviews. These industry experts have the following
253 backgrounds: Expert A is an internationally renowned building information modelling consulting expert
254 with experience in design, standards development, and technology management, Expert B is a quality
255 control manager with experience in inspection of assemblies in offsite construction, and Expert C a lead
256 welding inspector with a background on industrial, commercial, and prefabricated steel assemblies.
257 Collectively, these experts provide a rich set of experiences on the design, inspection of, and
258 implementation of tolerance management practices in construction projects across Europe and North
259 America, predominately within large AEC firms. Two semi-structured interviews were held with each
260 expert (during the development process); each ranging in length between 30 and 60 minutes. Through this
261 consultation, the following criteria were selected for the framework: identification of tolerance risks,

262 specification of tolerance values, tolerance analysis, tolerance allocation, and communication of tolerance
263 information. These criteria were selected using external expertise to ensure the developed domain model
264 remained pragmatic and relevant to current industry practice.

265 **3.4 Model Development Process**

266 ToleranceDM was developed incrementally using refinement cycles consisting of concept brainstorming,
267 mapping, and organization into inheritance hierarchies, and then reviewing against a body of case studies.
268 The development team (i.e., the authors) serve as five multi-disciplinary experts with the following
269 backgrounds: two with a background in knowledge engineering and artificial intelligence for AEC, two
270 experts on tolerance management in construction with backgrounds in dimensional inspection consulting,
271 and one with a background in simulation, expert elicitation systems and construction innovation. As a key
272 driving motivation towards automated tolerance management in construction, the authors have developed
273 proof of concept software tools for tolerance management in parallel with the development of the DM.

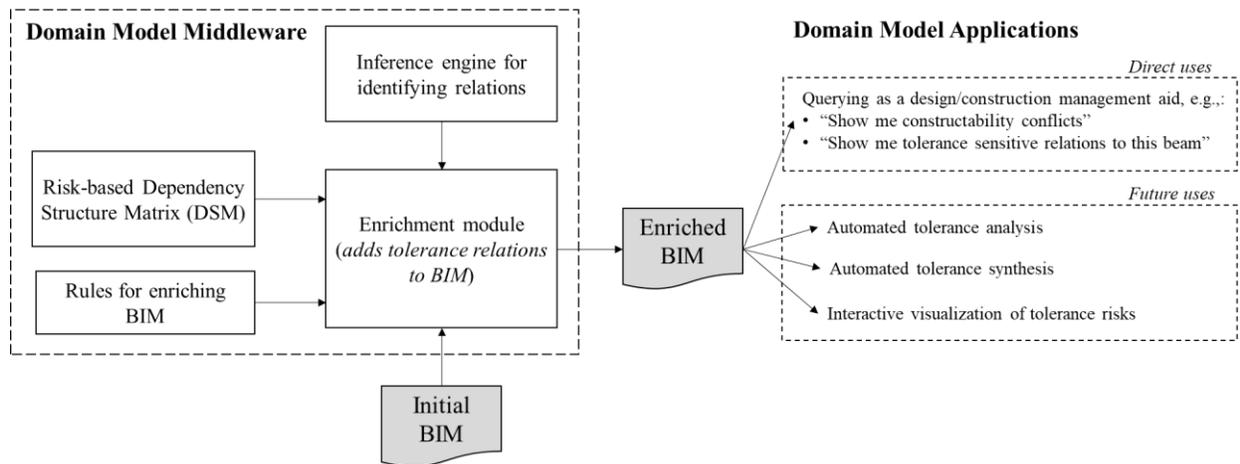
274 With respect to scoping, in the first version of ToleranceDM, mitigation is only incorporated into the meta-
275 model (i.e., introduced as concepts at the highest level of abstraction). As such, mitigation concepts have
276 not been as fully developed as other aspects of ToleranceDM, as reflected in their superficial treatment in
277 the description of ToleranceDM workflow processes (Section 4) and the integration of ToleranceDM into
278 the IFC standard. In future iterative refinement cycles these aspects will be dealt with in significantly more
279 depth.

280 **3.5 Refinement and Validation**

281 The initial validation process consisted of collecting feedback from three external experts using semi-
282 structured interviews. Prototype analysis tools are validated on BIMs from real buildings (rather than purely
283 conceptual models) to ensure that the DM is practical and applicable to real-world construction projects.
284 This drives the development of the DM with the inclusion of concepts that are determined to be valuable
285 or necessary to undertake the analysis tasks required by the cases, and helps to refine the DM by ensuring
286 that redundant or unused concepts can be highlighted and removed, ensuring that the DM is lean and
287 pragmatic. As a result of the feedback and instantiation of DM classes through real projects, the model was
288 refined and queried to ensure responses were both valid and adequate.

289 **4.0 Tolerance Management Domain Model (ToleranceDM)**

290 As outlined in Figure 1, the proposed workflow for ToleranceDM takes an initial BIM and through a
291 sequence of inference rules based on expert knowledge about identifying, assessing, and mitigating
292 tolerance-related risks, automatically parses key tolerance relationships to create a semantically rich BIM
293 with tolerance management concepts such as tolerance categories and mitigation strategies. The enriched
294 BIM can then be used to perform a series of useful analyses and simulations to conduct and support effective
295 tolerance management. For clarity, the scope of this present research is on the development of the DM and
296 practical direct use-cases, which is essential to move towards automated tolerance management and can be
297 considered as a starting point for similar research efforts. A more comprehensive examination and
298 demonstration of potential use-cases of BIMs enriched through ToleranceDM will be addressed in future
299 work.



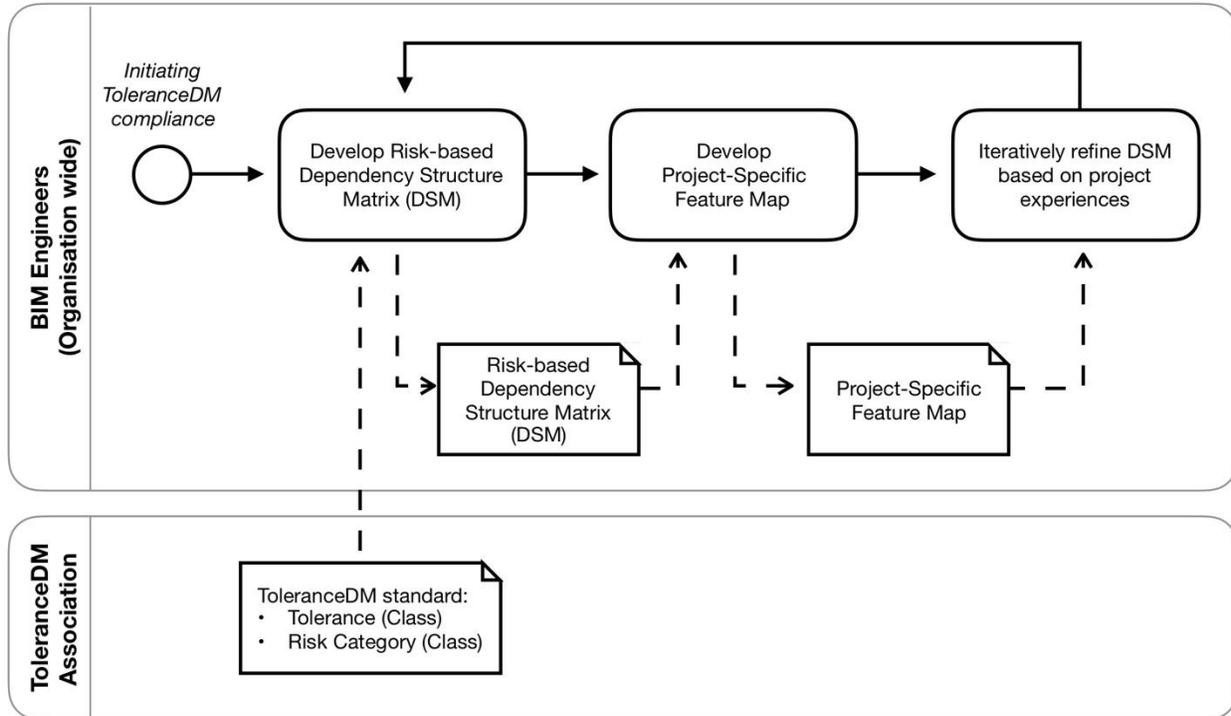
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301 **Figure 1: Overall workflow for the Tolerance Management Domain Model (ToleranceDM)**

302 More concretely, the current workflow utilising ToleranceDM is divided into two processes, each illustrated
 303 as Business Process Model Notation diagrams in Figure 2 and Figure 3. The BPMN swim lanes (large,
 304 rounded marquee rectangles) denote the division of roles between different actors, and BPMN activities
 305 (small, rounded rectangle boxes) and artefacts (dog-eared boxes) detail which knowledge is available at
 306 each stage in the two processes.

307 The first process (Figure 2) is undertaken by BIM engineers at an organisational (company) level. Initially
 308 the organisation develops their own custom, tailored Risk-Based Dependency Structure Matrix (DSM) that
 309 expresses the tolerances specific to the projects that they are involved in. We envision in the future that this
 310 step will be significantly supported through a community-wide effort in developing open libraries of
 311 template DSMs that capture domain specific knowledge about common tolerance sensitive relations
 312 between particular building features. ToleranceDM provides the modelling language "building blocks" that
 313 describes the classes of tolerance sensitivity, the current version of which we present in Section 4, especially
 314 Table 1, Figure 4 and Figure 6.

315 Next, BIM engineers specify a mapping between BIM products and their in-house custom product types.
 316 That is, we determined through our case study of the Oastler building that many critical tolerance
 317 relationships exist between product types that did not align well with the BIM data exchange format that
 318 was used (e.g., slabs that formed parts of the foundation, and a particular architectural feature referred to as
 319 "fins" in the Oastler building). Thus, from the perspective of ToleranceDM, rather than tying the
 320 identification of products in the DSM to a particular BIM standard (e.g., IFC), the workflow introduces an
 321 additional abstraction layer in which an organisation "maps" BIM products into their own custom types. In
 322 principle, this is an optional step and an organisation may opt for a 1-to-1 relationship between product
 323 types in their DSM and the underlying BIM standard. The DSM and product mapping artefacts are
 324 subsequently iteratively refined during and between projects.

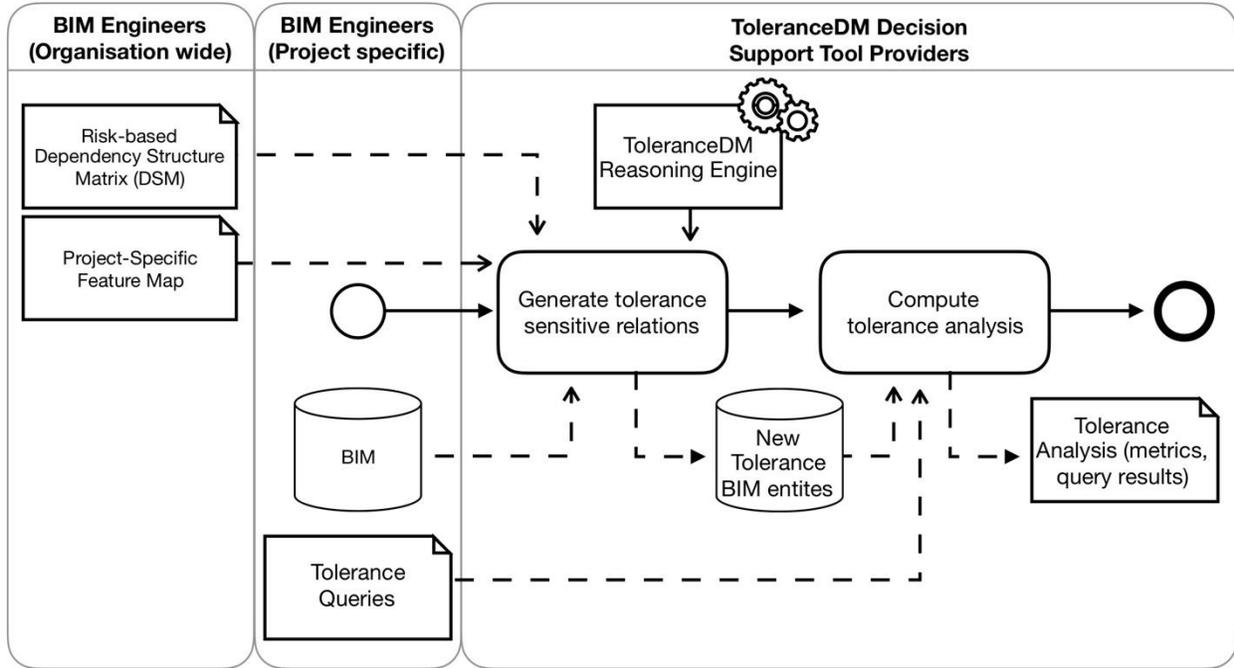


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326 **Figure 2: BPMN diagram illustrating the first workflow process for utilising ToleranceDM.**
 327 **Organisations develop, maintain, and iteratively refine DSM and feature maps to be used in the second**
 328 **workflow process.**

329 The second process (Figure 3) is undertaken by BIM engineers on a project-specific level. The two output
 330 artefacts from the first workflow process, namely the DSM and feature map, are combined with the BIM
 331 of a particular project at hand in order to generate the project-specific set of tolerance sensitive relations
 332 between products. This is accomplished automatically by the ToleranceDM Reasoning Engine; in this paper
 333 we have developed a prototype system as a proof of concept, and to demonstrate analysis functionality
 334 provided by our ToleranceDM approach.

335 The newly created tolerance sensitive information is specifically expressed in the form of new BIM
 336 relationships injected into the model: new instances of the class "Tolerance Sensitive Relation" that hold
 337 between various products in the BIM. The particular subclass relationship determines the refined semantics
 338 of the tolerance relationship, as detailed in Figure 4, Figure 6 and Table 1. Based on these new relationships,
 339 various metrics are computed that provide building information modelling engineers and project managers
 340 with new information about the planned construction from the perspective of tolerance sensitivity. The
 341 analysis is tailored by the building information modelling engineers in the form of "tolerance queries" (or
 342 "filters"), which we exemplify in the case study in Section 5.



343

344 **Figure 3: BPMN diagram illustrating the second workflow process for utilising ToleranceDM with**
 345 **respect to a specific project.**

346 In this study we propose a rule-based reasoning approach and a prototype software system for deriving,
 347 querying, and analysing tolerance relationships in large-scale BIM models. We demonstrate the practical
 348 aspects of our implementation on a real use case and emphasize modular and configurable rule encodings
 349 so they can be easily adapted to *general* tolerance management scenarios.

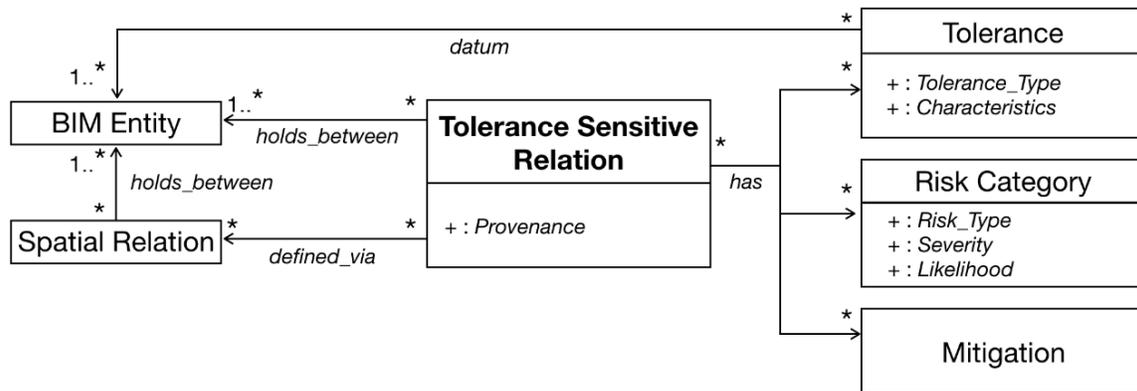
350 **4.1 An Abstract Structure of Tolerance Management**

351 In this section, definitions are provided for the most general concepts and their relations with respect to
 352 tolerance management (from an ontological perspective), and a selection of class refinements derived from
 353 literature and other resources described in Section 3. This provides a conceptual language for semantically
 354 enriching a BIM, and subsequently facilitating tolerance management querying and analysis.

355 As illustrated in Figure 4, the most abstract structure of tolerance management concepts consists of
 356 *Tolerance Sensitive Relations* that hold between BIM entities via spatial relations. If such a relation holds
 357 between entities, then deviations during manufacturing, placement, and aggregation of those entities beyond
 358 a threshold will have a specific, negative impact on the overall project. In this research, the term *BIM entity*
 359 is further discretized into components (i.e., construction objects that aggregate into assemblies), and
 360 component-parts, herein referred to as parts (i.e., specific geometric aspects of a component such as the top
 361 surface of a beam). The definition of which entities are in a tolerance sensitive relation is the formalisation
 362 of knowledge from the tolerance community. For example, as shown in Figure 5:

- 363 • the notion that "*deviations in the placement of two adjacent slabs can result in a dangerously large*
 364 *gap*" is expressed by assigning a (binary) tolerance sensitive relation between slabs that meet flush
 365 horizontally (i.e., vertical faces of the defining geometries "touch", or have external contact).
- 366 • the notion that "*deviations in the parallel alignment of two beams that frame an opening for a door*
 367 *can result in the door no longer fitting*" is expressed by assigning tolerance sensitive relations

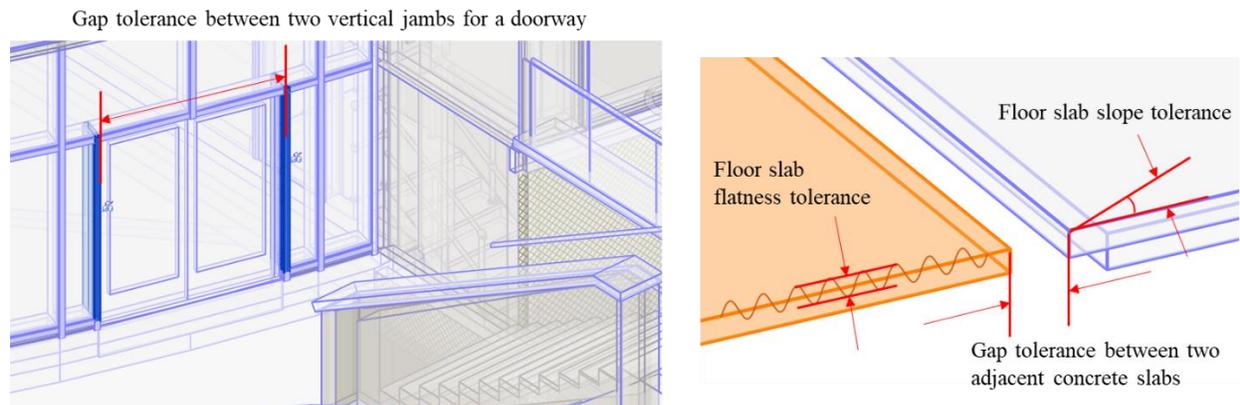
368 between any two beam entities (the entity types) that both have spatial contact (the spatial relation)
 369 with the same door entity.
 370 • the notion that "deviations in the flatness of a slab can result in unwarranted slopes for mobility
 371 impaired patients in a hospital" is expressed by assigning (unary) tolerance sensitive relations to
 372 slabs in locations occupied by such patients.



373

374 **Figure 4: Abstract structure of high-level tolerance management concepts.**

375



376

377 **Figure 5: Demonstrating how tolerance sensitive entities can be formalised.**

378 These tolerance relations are introduced into a BIM on the same ontological level as other entity relations
 379 such as *contact* between two entities that have physical contact, or *voids object* between a wall and an
 380 opening i.e., a region of empty space. The *arity* of a tolerance sensitive relation specifies the number of
 381 entities between which the relation holds. A unary relation holds over a single entity, equivalent to the
 382 concept of an entity property, e.g., the tolerance sensitive quality of slab flatness is modelled as a unary
 383 tolerance sensitive relation holding over individual slabs.

384 Each tolerance sensitive relation has attributes of *provenance* and *risk*:

- 385 • *Provenance* refers to the source of the tolerance sensitive relation class: *normal* (derived from
 386 guidelines and standards); *special* (based on expert input for certain parts); *specific* (based on
 387 expert input for the entire building structure) [47].
- 388 • *Risk* refers to the frequency and impact of tolerance conflicts.

389 Each tolerance sensitive relation is associated with:

- 390 • *Tolerance* constraints that define the limits within which deviations will not result in risk category
391 impacts, as defined in Section 2.1 and 2.2. Table 1 presents further details on the information
392 captured in the Tolerance class, adapted from the GD&T ontology [48]. In Table 1, the concept of
393 datum as part of GD&T refers to a theoretically exact axis, point or plane from which the
394 geometric characteristics or location of a feature (e.g., size or surface) are established [29].
- 395 • *Risk Category* effects that result from tolerance conflicts, as defined in Section 2.2, consisting of
396 a risk *type* (structural safety, constructability, aesthetic, functionality) qualitative measures of
397 severity and likelihood (low, medium, high, extreme).
- 398 • Mitigation strategies that can be employed to alleviate the impact of risk categories in case of
399 tolerance conflicts.

400 **Table 1: Information expressed in the ToleranceDM Tolerance Sensitive Relation class, adapted from**
401 **GD&T ontology [48].**

Tolerance Type	Characteristics	Datum Req'd?	Applications
Size: spatial extent of an entity	Dimensions	No	To control dimensions of any component
Form: the shape of a surface.	Straightness: allowed deviation of a surface along a line.	No	To control the beams and columns that are prone to deformation.
	Flatness	No	To control the flatness of floor surfaces.
Orientation: relationship between features and datums at particular angles.	Perpendicularity (surface): variation allowed over a form being parallel to the datum plane.	Yes	To control components for which plumbness tolerances are a major concern.
	Parallelism: variation allowed over an entire plane, from being parallel to the reference plane.	Yes	To control surfaces that should maintain a constant distance.
Location: position of the feature relative to a datum.	Tolerance of Position (TOP): allowed deviation of a feature's axis from the True position.	Yes	To control (1) the location of features of size such as columns and beams, and (2) the distance between those features of size

402

403 In the following sections, we define particular refinements (subclasses) of the Tolerance Sensitive
404 Relation class.

405 **4.2 Tolerance Interdependency Matrix**

406 To capture the interdependency of components and parts with respect to tolerances, a dependency structure
407 matrix is used. This matrix is referred to as the *Tolerance Interdependency Matrix* since it outlines the direct
408 relationships within and between components and parts. The tool is versatile with respect to the LOD that
409 components are related, e.g., it is used to express dependencies between component types such as
410 foundations and walls, and dependencies between component parts such as the top surface of foundations
411 in contact with the lower surfaces of a wall.

412 Assembly components and parts are listed both in the rows and columns of the matrix. Each component
413 and part are represented with the symbolic notation C_T^P with subscript T indicating the component type and
414 superscript P indicating the part. If there is any physical connection (i.e., joint or interface) between the

415 component (and part) at row i , and component (and part) at column j , the interrelated cell is filled with a
 416 value according to its tolerance type; otherwise, it is filled with 0. The types of tolerances considered here
 417 include flatness (F), parallelism (PA), positional (PO), and perpendicularity (PE). The process of capturing
 418 tolerance interdependency can be formalized algebraically as follows. First, let M denote an $n \times n$ Tolerance
 419 Interdependency Matrix, and let m_{ij} denote the tolerance interdependency at the i -th row and j -th column,
 420 for $i, j \in \mathbb{N}$, such that $1 \leq i, j \leq n$. For all i, j from 1 to n :

- 421 • $m_{ij} \in \{F, PA, PO, PE\}$, if C_i has a tolerance interdependence with C_j .
- 422 • $m_{ij} = 0$, otherwise

423 The rows and columns are ordered according to the temporal sequencing in which components are installed
 424 with respect to preceding components. The matrix, when populated with binary relations, is not necessarily
 425 symmetric because the sequence of installation/erection of components is also being captured. Furthermore,
 426 tolerance interdependencies which are self-intersecting can be used to denote that a component or part has
 427 an intra-object tolerance relation (e.g., flatness).

428 Once the matrix is populated and the interdependencies are captured, a final additional step is to colour the
 429 cells based on predefined levels of risk which can be defined by (1) the collective decision of project
 430 representatives responsible for tolerance management, and/or by (2) predetermined risk of connections
 431 found from the literature [13]. The basis of this risk colorization is representative of adversarial impacts on
 432 structural safety, constructability, aesthetics, and functionality. For instance, red denotes high tolerance
 433 risk, orange denotes medium tolerance risk, and green denotes low tolerance risk. Based on this
 434 categorization, it is possible to capture risk associated with connections as follows:

- 435 • **Low risk connections:** Remedial costs are non-negligible (yet not significant), and the
 436 functionality is adversely affected but the functionality of the connection still conforms to the
 437 specifications.
- 438 • **Medium risk connection:** Remedial costs are higher, and the functionality is adversely affected in
 439 such a way that the connection does not function as intended.
- 440 • **High risk connection:** Remedial costs are highest and there is a high risk to safety.

441 Table 2 depicts the notation for developing the Tolerance Interdependency Matrix. The left column denotes
 442 preceding component sequencing while the top row denotes succeeding component sequencing. For a
 443 sample completed Tolerance Interdependency Matrix, the reader is directed to Appendix A which
 444 corresponds to the case study presented in this paper.

445 **Table 2: Tolerance Interdependency Matrix Notation**

		C ₁			C ₂			C ₃		
		C ₁ ¹	C ₁ ²	C ₁ ⁿ	C ₂ ¹	C ₂ ²	C ₂ ⁿ	C ₃ ¹	C ₃ ²	C ₃ ⁿ
C ₁	C ₁ ¹	m_{11}	m_{1j}
	C ₁ ²							
	C ₁ ⁿ						
C ₂	C ₂ ¹					
	C ₂ ²				
	C ₂ ⁿ				
C ₃	C ₃ ¹			
	C ₃ ²		
	C ₃ ⁿ	m_{ij}								m_{ij}

446

447 A fully developed serialization of a DSM is future work. For the initial version, we serialise DSMs in a
448 comma separate format (CSV). Column and row headers are represented using the format (with all spaces
449 in labels replaced by underscore “_”):

```
<Component> : <Part>  
e.g., “Concrete Slab : Top Surface”
```

450

451 Cell entries are a list of symbols in square brackets separated by semicolons based on a simple coding
452 system: F= Flatness tolerance, PA: Parallelism tolerance, PO: Position tolerance, PE: Perpendicularity
453 tolerance (e.g., [F,PO] means the corresponding cell entry has flatness and position tolerance sensitivity”).
454 For example, the first three columns and rows of the example DSM in Appendix A is serialised in CSV
455 format as follows:

```
Foundation : Top_Surface, Concrete_Slab : Top_Surface, Concrete_Slab : Bottom_Surface  
[], [], [F]  
[], [], []  
[F], [], []
```

456

457 4.3 Operationalizing ToleranceDM

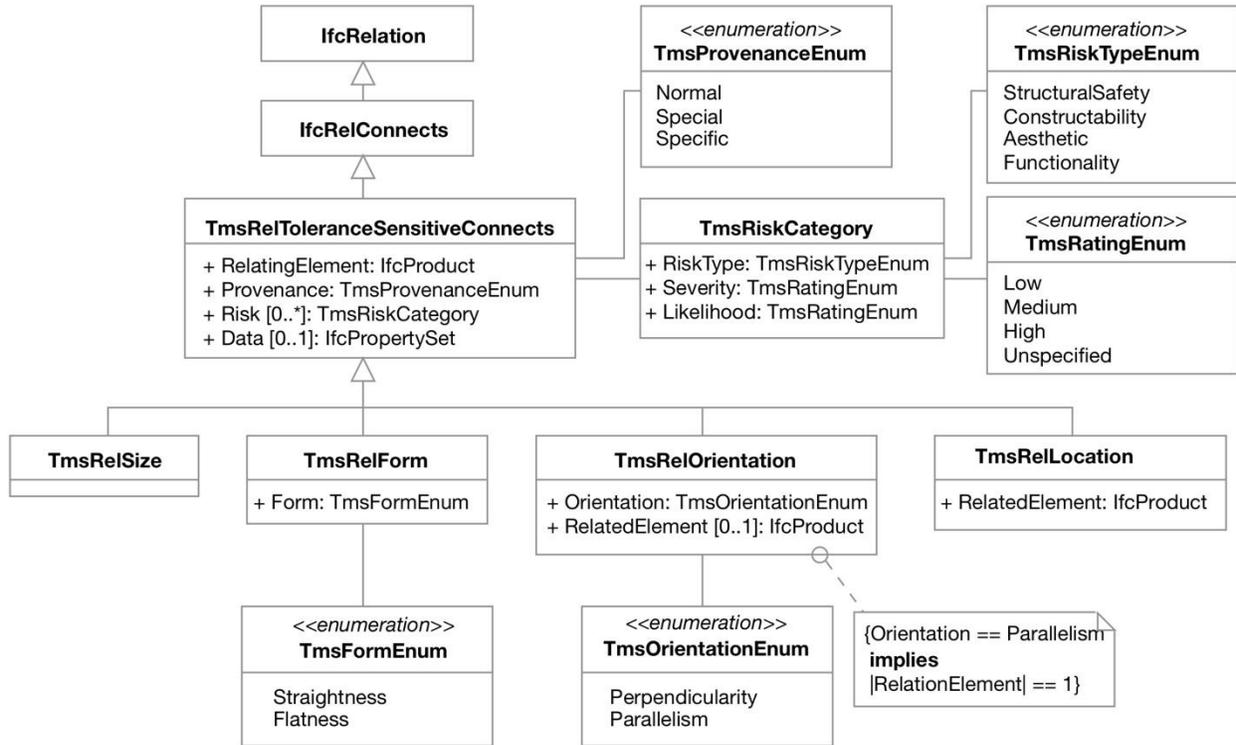
458 In this section, we describe the task of *semantic enrichment* for augmenting a BIM with tolerance sensitive
459 relations. These new relations are then used to provide project stakeholders with a range of *query services*
460 concerned with identifying components in the BIM for which tolerance is a critical concern.

461 4.3.1 BIM Semantic Enrichment

462 Within the context of BIM, a building component (i.e., an “object”) consists of a type, e.g., IfcDoor, and a
463 unique identifier, e.g., a GUID. Components can be assigned to one or more geometric representations, e.g.,
464 IfcRepresentation including 2D/3D surface representations etc. An n -ary relation has a type, e.g.,
465 IfcRelVoidsElement, and is assigned to n components, meaning that the relation holds between those
466 components.

467 An instance of a BIM, denoted B , consists of a set of building components C and relations R between those
468 components, $B = C \cup R$. Each component in C belongs to a hierarchy of building entity class types, e.g.,
469 IFC classes IfcRoot, IfcProject, IfcDoor etc. Each component has zero or more geometric representations
470 such as 3D meshes, 2D polygonal footprints, etc. This research denotes a geometric representation g of
471 component c using the predicate $rep(g, e)$. Let S_1, \dots, S_m be a set of predefined spatial relations defined over
472 specific types of geometric representations such as intersects, meets_flush, is_flat, etc. For brevity, a tuple
473 of building components c_1, \dots, c_k in C^k (for $k > 0$) is considered to satisfy a given spatial relation S_i , denoted
474 $S_i(c_1, \dots, c_k)$, if their corresponding geometric representations satisfy the spatial relation, $S_i(g_1, \dots, g_k)$ such
475 that $rep(g_j, e_j)$ for $1 \leq j \leq k$.

476 *BIM augmentation* consists of identifying new tolerance sensitive relations that hold between tuples of
477 components in C , and adding these relations to the set of BIM relations R . In this first version of
478 ToleranceDM, a general "ToleranceSensitiveRelation" relation is defined within the IFC standard. As
479 shown in Figure 6, the tolerance sensitive relation is a subclass of IfcRelConnects; in keeping with IFC
480 naming conventions the new relation is called *TmsRelToleranceSensitiveConnects*.



481
 482 **Figure 6: UML class diagram depicting that the new *TmsRelToleranceSensitiveConnects* relation (and**
 483 **the refining subclasses are a subclass of *IfcRelConnects* within the IFC standard.**

484 The *IfcRelConnects* relation has been chosen as a suitable superclass owing to the semantics of that IFC
 485 class expressing "a connectivity relationship that connects objects under some criteria [such that] subtypes
 486 of the relationship define the applicable object types for the connectivity relationship and the semantics of
 487 the particular connectivity" [49].

488 *IfcRelConnectsElements* was also a viable candidate, however this was rejected as it is constrained to be a
 489 *binary* relationship that always holds between exactly two entities. Tolerance sensitivity, as an abstract
 490 relationship, requires more flexibility. For example, "flatness" is more appropriately modelled as a *unary*
 491 relation.

492 *IfcPropertySets* were also under consideration as a means of integrating ToleranceDM into IFC. However,
 493 property sets assign properties to products, rather than expressing new relationships *between* products.
 494 ToleranceDM takes the modelling stance that "tolerance" as a concept is captured most appropriately, with
 495 respect to semantics as a relationship that can hold between products. That is, many kinds of tolerances are
 496 relative between product instances, e.g., "parallelism" is a tolerance on the relative orientation of two
 497 products.

498 In terms of scope for the first version of ToleranceDM, the assignment of numerical values to tolerance
 499 parameters is kept at a general level (also referred to as tolerance *allocation* in product design), e.g.,
 500 specifying an exact numerical positional distance threshold for a particular *TmsRelLocation* relation
 501 instance. The issue from a modelling perspective is that various construction projects need significant
 502 flexibility in how numerical information is to be interpreted. For example, considering "flatness" one option
 503 would be to enforce a "flatness" metric to define a threshold, although any chosen metric may conflict with
 504 an organisation's preferred standard approach. Thus, rather than enforcing metrics and structure

505 prematurely, all `TmsRelToleranceSensitiveRelations` have an optional "Data" attribute that refers to an
506 `IfcPropertySet`. This provides a high level of versatility and may later be revised when further evidence has
507 been collected on the most useful ways of introducing more structure into these metrics, from industry
508 practitioner interaction and case study analyses (as part of the IDEF5 refinement and validation modelling
509 development stage).

510 As described in Section 3.4, a more detailed treatment of mitigation is left for future version of
511 `ToleranceDM` and is thus mitigation concepts are not integrated into IFC in this first version. Also,
512 `TmsRiskCategory` is a subclass of `IfcRoot` in this version of `ToleranceDM`. This relationship was omitted
513 from the diagram to reduce visual clutter.

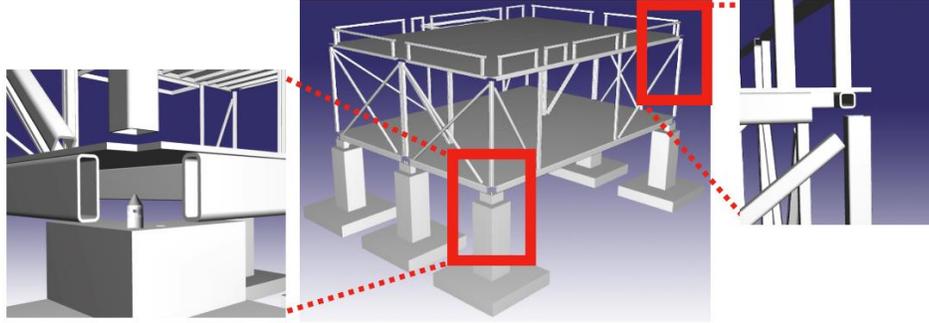
514 The first version of `ToleranceDM` supports 3D meshes as the geometry representations for components. A
515 uniform treatment of disparate geometric representations from a BIM/IFC is achieved through
516 `IfcOpenShell`'s default Delaunay triangulation. The geometry processing typically takes a few minutes for
517 a BIM with 10^4 objects but only must occur once. A 3D point $p_i=(x_i, y_i, z_i)$ is a 3-tuple of real numbers. A 3D
518 triangle is three vertices defined by distinct 3D points p_1, p_2, p_3 . A 3D mesh g is a set of 3D triangles referred
519 to as *faces*. The distance between two meshes g_1, g_2 is the minimum distance between every pair of triangles
520 t_i, t_j such that t_i is a face in g_1 , and t_j is a face in g_2 .

521 4.3.2 Inferring Contact in BIM

522 In this version of `ToleranceDM`, it is assumed that semantic contact information has been omitted from the
523 original IFC, e.g., no products are assigned the `IfcRelConnectsElement` relation, due to a modelling
524 oversight. If such semantic information is available then the task of introducing tolerance relations is
525 simplified, as semantic contact does not need to firstly be inferred based solely on the geometry of the
526 products.

527 A key challenge in tolerance-based model augmentation is inferring spatial contact between components.
528 The primary source of information used to infer contact is the geometry associated with BIM components.
529 However, contact between two components *does not imply* that their geometric representations have zero
530 distance between them in a BIM:

- 531 • In reality, a building is not static, and components continuously deform (e.g., expand or shrink).
532 The BIM designer may therefore intentionally leave a gap between two components with contact
533 so that any building movement would not lead to physical clash between them.
- 534 • The BIM may be modelled at a reduced LOD meaning that certain joining components (e.g., bolts,
535 gusset plates, etc.) are omitted. For example, Figure 7 illustrates a BIM (referred to as "Simple
536 Modular") in which brace components are intended to connect to beams in the design. However,
537 owing to the selected LOD by the BIM designer, the geometric representations are disconnected
538 (i.e., having a minimum distance greater than zero).
- 539 • The exact placement of components may not be precisely known, especially in the earlier stages of
540 design. In this case, the geometry in a BIM may only be a coarse approximation of the intended
541 final placement, and thus, geometries of two components may be disconnected although the
542 designer intends that they have contact. This is also reflected in different model view definitions
543 (MVDs) that may be used in a project – given certain views, some components will be omitted
544 from an MVD, resulting in contact being more complicated to infer explicitly from the raw
545 geometry during model exchange between stakeholders.



546

547 **Figure 7: Example “Simple Modular” BIM in which components that are intended to have contact**
 548 **have geometric representations that are disconnected. Interpreted literally, the brace components are**
 549 **not resting or attached to any other component, and would fall, making the BIM non-constructable.**

550 An automated tolerance management software tool that has industry value and impact must nonetheless be
 551 capable of inferring the designer’s *intention* of spatial contact between such components in the design.
 552 Thus, the inference of a contact relation between two components is only a *hypothesis*, justified by *evidence*
 553 in the form of the given geometric representations in the BIM, and background knowledge about physics,
 554 building construction, and BIM levels of development. For clarity, we distinguish these concepts with the
 555 terms *intended contact* (i.e., cases where the designer intends components to have contact) and *geometric*
 556 *contact* (i.e., when the 3D geometric representations of two components has zero distance between them)¹.

557 Therefore, despite BIM components not strictly achieving geometric contact, it is argued that the intention
 558 of contact is represented by information in the given (disconnected) geometric configuration and the
 559 semantics of the component types, within the context of tacit knowledge about buildings. For example, a
 560 knowledgeable construction engineer will be confident that certain braces illustrated in Figure 7 are
 561 intended to have contact with certain beams due to:

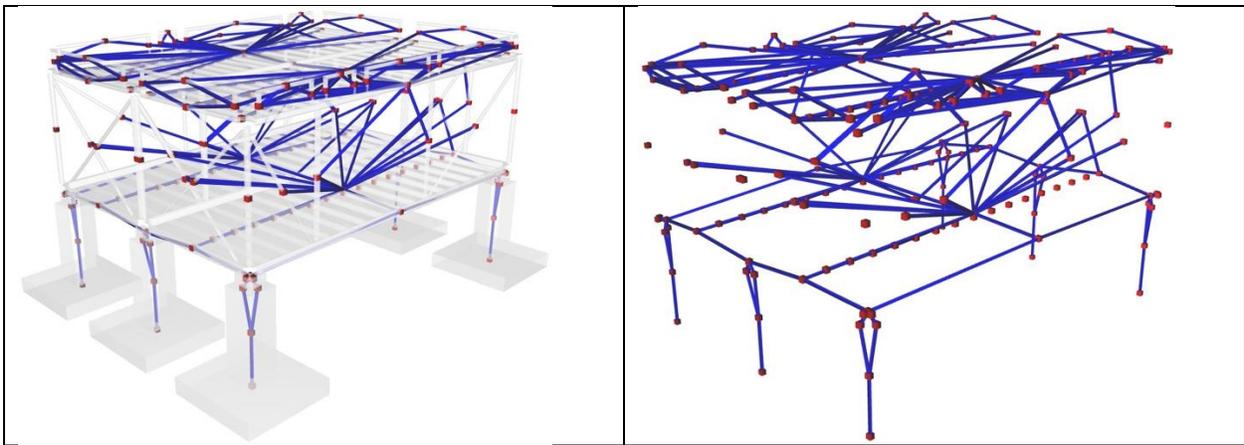
- 562
- the spatial arrangement of the components (proximity, orientation).
 - the component types (i.e., braces typically connect with beams).
 - the necessity of their contact for a coherent BIM - i.e., if they did not have contact, then the parts would be illogically "floating" in free space and thus the BIM would not be stable, safe nor constructible.
- 566

567 The task of hypothetically inferring contact relations can be addressed within a framework of logical
 568 abduction. For simplicity, in this first version, an optimistic (or aggressive) inference policy is adopted.
 569 That is, if the distance between two component (or part) geometries is within a specified threshold then
 570 contact is hypothesized. Based on the LOD framework used in this research [19], a minimum level of
 571 development required for ToleranceDM is LOD 200. At this level, elements are considered to be generic
 572 geometric placeholders, but may be recognizable as the components they represent particularly for
 573 rectilinear objects such as concrete footings or steel HSS members. At LOD 100, elements are not
 574 considered to be geometric representations and therefore there is not enough information to infer contact
 575 between components.

¹ These concepts are different from the semantic relation IfcRelConnects which does not imply geometric or intended contact. IfcRelToleranceSensitiveConnects is derived from a BIM using abduction, e.g., if they are justified by background knowledge and consistent with current observations. Our connection finding algorithm is designed to be modular and configurable, so users can refine it by object type, path criticality, node connectivity, etc. and can optionally introduce all "found contact" relations as new instances of IfcRelConnects.

576 Having generated contact relations, a contact graph is subsequently derived by taking components (or parts)
 577 as nodes, and contact relations between components (or parts) as edges between the corresponding nodes.
 578 A set of contact relations is *valid* if the contact graph is connected, i.e., there is a path through the contact
 579 graph between any pair of nodes. If the set of contact relations is *invalid*, then some components may be
 580 “free-floating” without ultimately being supported by foundation components, suggesting that either
 581 necessary contact relations have erroneously not been inferred, or that the BIM cannot be constructed.

582 For example, Figure 8 illustrates a derived contact graph visualised together with the geometry of the
 583 components. Components are represented by small red boxes (graph nodes) and contact between
 584 components is represented by thin blue cylinders (graph edges). Nodes have been placed approximately in
 585 the centre of the corresponding component mesh (calculated as the mean of the mesh vertices). In the right
 586 subfigure, red nodes can be seen to not have any connecting edges and thus this particular set of
 587 hypothesized contact relations is invalid, requiring the distance threshold for inferring contact to be
 588 increased.



589
 590 *Figure 8: Derived contact graph visualised with the “Simple Modular” BIM geometry (left) and the*
 591 *graph visualised in isolation (right).*

592 4.3.3 BIM Tolerance Analysis and Querying

593 Having inferred contact relations, a Tolerance Interdependency Matrix is used to augment a BIM with
 594 tolerance sensitive relations. The matrix identifies connections and tolerance risks in those connections.
 595 The Tolerance Interdependency Matrix utilised to develop ToleranceDM can be re-used as a benchmark
 596 for next projects of the same type. Users can then add/remove connections or change the associated
 597 tolerance risks based on the type of the project, thus saving time required for the initial setup of
 598 ToleranceDM. The pseudocode algorithm is as follows.

599 **Algorithm 1. Augmenting BIM with Tolerance Sensitive relations.**

```

Input: Matrix M, Building_Information_Model BIM
Output: Building_Information_Model

1: For each cell in M with value other than “0”:
2:   Get the component/part class type label of the cell's row (C1)
3:   Get the component/part class type label of the cell's column (C2)
4:   For each instance c1, c2 in BIM component/parts C1, C2:
5:     If c1, c2 have contact then:
  
```

6: Generate a new tolerance sensitive relation between instances c_1 , c_2 (with risk and impact information expressed in the Matrix) and add to BIM
 7: return BIM

600

601 For example, Table 3 presents a Tolerance Interdependency Matrix that consists of just one cell indicating
 602 that the contact between slabs and columns has a high risk (i.e., red colour) – in this case corresponding to
 603 a positional tolerance (i.e., “PO”). Information about the specific impact is also optionally encoded in the
 604 Matrix, i.e., the example Matrix indicates that the risk is to constructability. Each instance c_1 , c_2 of an
 605 IfcSlab and IfcColumn such that they have contact (as derived in the previous section) results in a new
 606 tolerance sensitive relation being created between c_1 , c_2 .

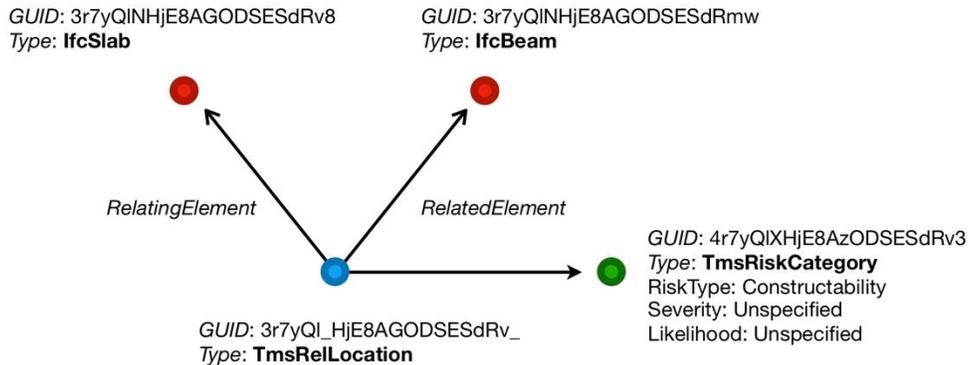
607 Figure 9 illustrates an extract of the knowledge graph that shows how the original IFC model is augmented
 608 with the new tolerance information in the form of relations and risk category entities. Figure 10 illustrates
 609 the application of the DSM in Table 3 to the modular BIM by colouring all components red that occur in a
 610 high-risk tolerance sensitive relation.

611 **Table 3: An example Tolerance Interdependency Matrix.**

	IfcColumn
IfcSlab	PO (constructability)

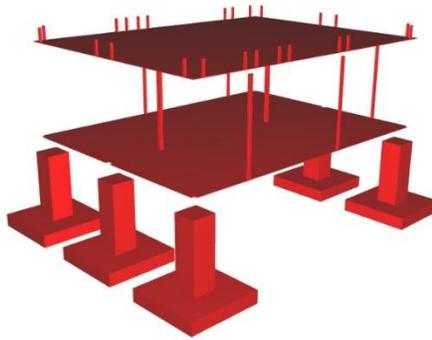
612

613



614

615 **Figure 9: Extract of knowledge graph to illustrate how the BIM is augmented with tolerance**
 616 **information. The original IFC file contained two products represented by the red nodes in the graph**
 617 **(IfcSlab and IfcBeam). The ToleranceDM reasoning system determined these products to have contact**
 618 **and based on the DSM (Table 3) the new tolerance sensitive relation TmsRelLocation is injected into**
 619 **the BIM (blue node) with its associated RiskCategory entity (green node).**



620
 621 **Figure 10: Visualising components in the “Simple Modular” BIM that occur in a high-risk tolerance**
 622 **sensitive relation in red, according to the Matrix presented in Table 3.**

623 Given an augmented BIM, a wide range of queries Q1-Q6 can be executed:

- 624 • Q1: Finding all components/parts that occur in an intended contact relation.
- 625 • Q2: Finding all components/parts that occur in a tolerance sensitive relation.
- 626 • Q3: Filtering Q1, Q2 according to risk level (low, medium, high).
- 627 • Q4: Filtering Q1, Q2 according to risk type (i.e., structural safety, constructability, aesthetic,
 628 functionality).
- 629 • Q5: Filtering Q1, Q2 according to component/part types (e.g., slabs, columns, etc.).
- 630 • Q6: Applying any combination of filtering options Q3-Q5.

631 Statistics can also be derived based on the above query results, as enumerated in S1-S3 below. For example,
 632 for a given component, one can count the number of other components that it has contact with, referred to
 633 as the degree of contact (i.e., using graph theory terminology in the context of the contact graph).

- 634 • S1: number of contact relations that a component/part occurs in (degree of contact)
- 635 • S2: number of tolerance sensitive relations that a component/part occurs in (degree of tolerance
 636 sensitivity)
- 637 • S3: taking the results from Q6 and applying S1, S2 (degree of query-refined contact or query-
 638 refined tolerance sensitivity)

639 Figure 11 illustrates a scatterplot comparing contact degree with component type for the “Simple Modular”
 640 BIM (corresponding to statistic S1). Each data point (“x” symbol) is a component in the BIM. The X-axis
 641 categorises components according to their type (e.g., slabs, columns, etc.). The Y-axis measures the degree
 642 of contact, i.e., the number of other components that a given component (marked “x”) has contact with.

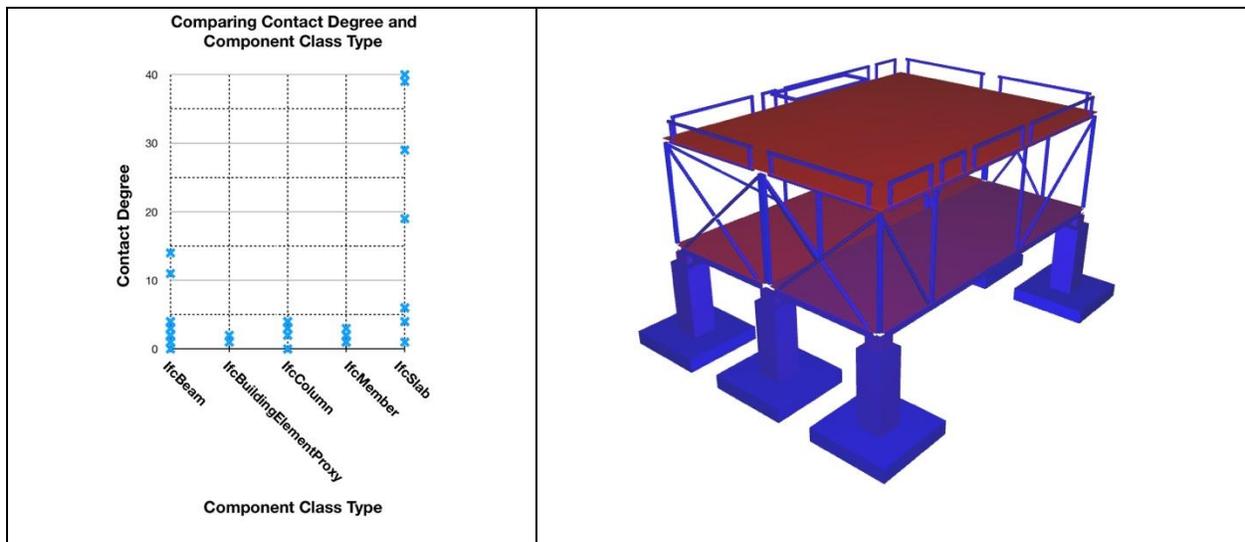
643 As an example of the analytical support that ToleranceDM provides, the scatterplot shows that slabs (as a
 644 class type) have both the highest contact degree, and the largest range of contact degrees, followed by
 645 beams, columns, members, and building element proxies. This suggests that slabs make up the contact

646 “hubs” of the construction. Buildings, building storeys and the site have no explicit geometric
647 representation in the given BIM, and thus have no contact relations².

648 Figure 11 also illustrates the relative degree of contact between components (corresponding to statistic S1).
649 Components visualised in red have a relatively high degree of contact (e.g., the central slabs), and
650 components visualised in blue have a relatively low degree of contact (e.g., foundation slabs and lower
651 columns).

652 To contrast contact and tolerance sensitivity, Figure 12 illustrates a scatterplot comparing tolerance
653 sensitive degree and component type in the “Simple Modular” BIM, based on the Matrix in Table 3,
654 corresponding to statistic S2. Comparing Figure 11 and Figure 12, it is observed that Figure 12 illustrates
655 the subset of contact relations that correspond to an entry in the DSM in Table 3. The colour gradients have
656 been recomputed to visually reflect the new range of degrees, i.e., from low (blue) to high (red) *tolerance*
657 *sensitivity* based on degree, as compared to *contact*.

658

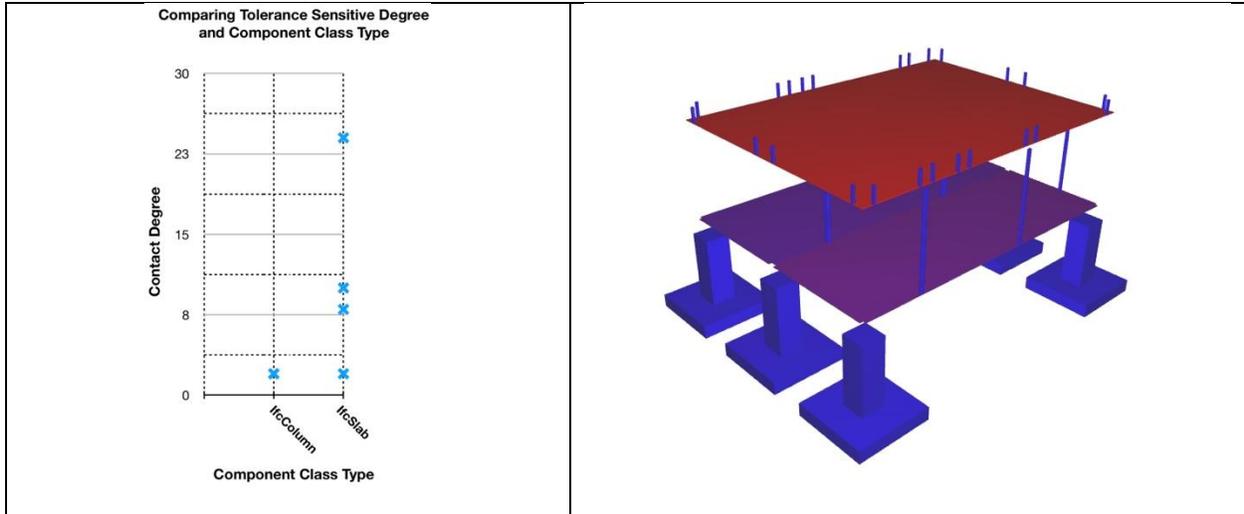


659

660 **Figure 11: (left) Scatterplot comparing contact degree with component class type for the “Simple**
661 **Modular” BIM. (right) Using a colour gradient (from red to blue) to visualise the relative degree of**
662 **contact of each component, where red corresponds to a high degree.**

663

² Components are organised into building storeys through the IfcRelContainedInSpatialStructure relation (and, in turn, storeys are composed to form the whole building through IfcRelDecomposes relation). The building storey could be assigned to the set of all geometric representations of contained components, providing some interpretation of contact between building storeys, buildings, and other components.



664
 665 *Figure 12: (left) Scatterplot comparing tolerance sensitivity degree (based on the Matrix in Table 3)*
 666 *with component class type for the “Simple Modular” BIM. (right) Using a colour gradient (from red to*
 667 *blue) to visualise the relative degree of tolerance sensitivity of each component, where red corresponds*
 668 *to a high degree.*

669 **5.0 Functional Demonstration**

670 This functional demonstration of ToleranceDM focuses on consolidating tolerance domain knowledge
 671 pertaining to BIM LOD 300 (since there are instances where both BIMs do not contain parts necessary for
 672 coordination of the element with nearby of attached objects, they cannot be considered to be fully within
 673 the LOD 350 designation). Two BIMs are used in this demonstration. The “Simple Modular” BIM
 674 (presented in Section 4.3) was developed for a prototypical modular construction project in Canada. Due to
 675 the simplicity of its building assembly, this BIM is investigated in this paper as a working model for
 676 developing ToleranceDM. The second BIM (“Oastler”) is a large public building with steel structure,
 677 composite steel deck-slabs, curtain walls, glazing, masonry panels, suspended floors and a roof. All ground
 678 floor slabs are comprised of reinforced concrete and bear directly onto the ground. The cost for this 7,500
 679 m² building was approximately \$37.4M. The bespoke curvature of the building and anodized aluminum
 680 fins attached to the structure, give it a distinctive architectural feature, while adding important tolerance
 681 sensitive connections. Table 4 presents geometry and model statistics of the two BIMs – of particular note
 682 is the difference in BIM sizes, both in the number of building components, and the complexity of geometric
 683 representations as 3D meshes, thus reflecting the ability to gauge the scalability of ToleranceDM.

684 *Table 4: Geometry and contact relation statistics for the demonstration BIMs.*

BIM	Components	Meshes	Triangles	Inferred contact relations	Contact degree		
					Min	Mean	Max
Simple Modular	211	206	54,864	252	0	2.45	40
Oastler	3,355	3,330	678,860	13,514	0	8.12	515

685

686 IFC BIMs were parsed using the IfcOpenShell tool suite,³ to extract component unique identifiers,
 687 component class types, and 3D meshes. The reasoning engine was developed using a combination of the
 688 logic programming languages Answer Set Programming and Prolog, based on the InSpace3D system [50].
 689 ASP and Prolog constitute the theoretical foundation of our software system in that every inference can be
 690 logically derived, thus *verifiable* and *explainable*. This is particularly important in the scope of tolerance
 691 management due to irreducible deviations from BIM geometry (two components are almost touching) from
 692 design intents (the components should be connected). Therefore, each tolerance relationship is contingent
 693 to a number of default assumptions and educated guesses about tolerance relationships. ASP and Prolog
 694 provides modifiable and extensible encodings for this additional knowledge in the form of defeasible rules,
 695 so the process of augmenting BIM with tolerance relationships is transparent and verifiable.

696 Firstly, the BIM was parsed into logic programming facts of the following form representing each
 697 component unique identifier and class type:

```
product(id("2aBHA8A3r75w4VRqHJ3d9h"),type(ifcBuilding)).
product(id("3r7yQINHjE8AGODSEsDRmc"),type(ifcBeam)).
...
```

698 The BIM geometries were parsed into facts about geometric representations of 3D meshes, consisting of
 699 3D point vertices, triangular faces, and face-normals (which are used to determine whether a given face is
 700 part of the top, bottom or sides of a product geometry):
 701

```
representation(surface_mesh,
  id("3r7yQINHjE8AGODSEsDRmc"),
  mesh(vertices([point(-6.964,-14.705,0.488),...]),
    faces([face(11,63,10),...]),
    face_normals([ vector(0,1,0),...])
  )).
```

702 The 3D axis aligned bounding box of each mesh was derived, represented as two 3D points (the left lower
 703 front corner, and right upper back corner). These are expressed as facts such as:
 704

```
representation(axis_aligned_box3d,
  id("3r7yQINHjE8AGODSEsDRmc"),
  box3d(point(-6.964,-17.852,0.304),
    point(-6.888,-14.705,0.507))).
```

705 Bounding boxes were scaled and translated into positive integer representations for more efficient
 706 processing:
 707

```
aabb("3r7yQINHjE8AGODSEsDRmc",(8001,10189,24891,8657,37295,26641)).
```

708 Contact was hypothesized based on bounding box intersection. Approximately 13,000 contact relations
 709 were derived out of approximately 5.4×10^6 distinct candidate pairs (i.e., where every pair of meshes is a
 710 candidate hypothesis, resulting in $N(N-1)/2 \approx 5.4 \times 10^6$ with $N=3300$). Two boxes intersect if their
 711 projections intersect in all three axes, as implemented in the following ASP program:
 712

```
%% Points of bounding box projected onto each axis
projection(Id, x, X1; Id, x, X2; Id, y, Y1; Id, y, Y2; Id, z, Z1; Id, z, Z2) :-
  aabb(Id, (X1, Y1, Z1, X2, Y2, Z2)).
```

```
%% Holds if either start/end point of Id1, projected onto Axis, is within
```

³ <http://www.ifcopenshell.org/>

```

%% the interval defined by Id2 points projected onto Axis.
point_intersects_line(Id1, Id2, Axis) :-
  projection(Id1, Axis, M),
  projection(Id2, Axis, Min), projection(Id2, Axis, Max),
  Min <= M, M <= Max.

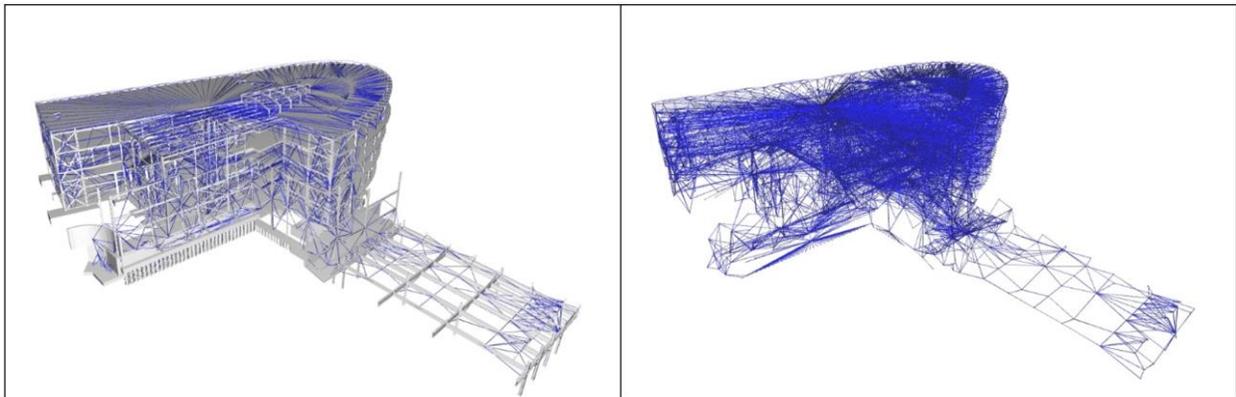
%% As above, but with Id1 and Id2 swapped
point_intersects_line(Id2, Id1, A) :-
  projection(Id1, A, M), projection(Id2, A, Min), projection(Id2, A, Max),
  Min <= M, M <= Max.

%% Components Id1,Id2 have contact if their bounding boxes intersect
%% in all three axes (x,y,z)
contact(Id1, Id2) :-
  aabb(Id1, _), aabb(Id2, _),
  Id1 < Id2, %% standard ASP approach to avoid symmetric and reflexive cases
  point_intersects_line(Id1, Id2, x),
  point_intersects_line(Id1, Id2, y),
  point_intersects_line(Id1, Id2, z).

```

713

714 Figure 13 illustrates the derived contact graph for the Oastler BIM.

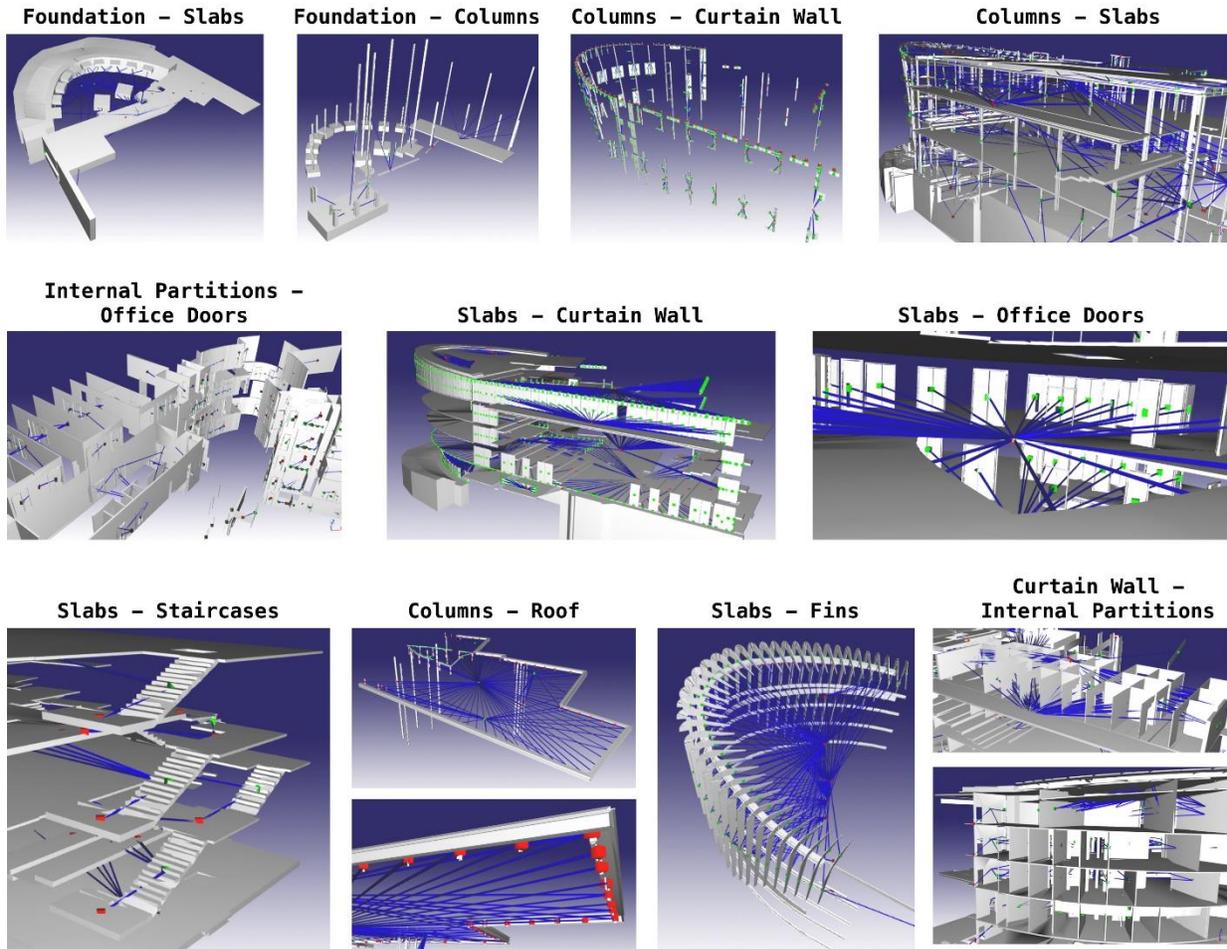


715

716 *Figure 13: Derived contact graph visualised with the “Oastler” BIM geometry (left) and the graph*
 717 *visualised in isolation (right).*

718 A tolerance interdependency matrix was created for the Oastler functional demonstration (Appendix A).
 719 There are three main steps used to infer the tolerance sensitive relations specified in the matrix. As described
 720 previously, the first step is to infer spatial contact relations between all components (discussed in more
 721 detail in Section 6.1). Class types such as foundations, stone cladding, internal partitions, and office doors
 722 were not explicitly defined in the given IFC of the Oastler building, and thus for the second step we hand-
 723 crafted a simple set of rules tailored to the Oastler BIM to identify which objects belonged to the relevant
 724 project-specific class. The third step consisted of deriving tolerance sensitive relations according to the
 725 class types specified in the matrix, and spatial contact relations inferred in the first step.

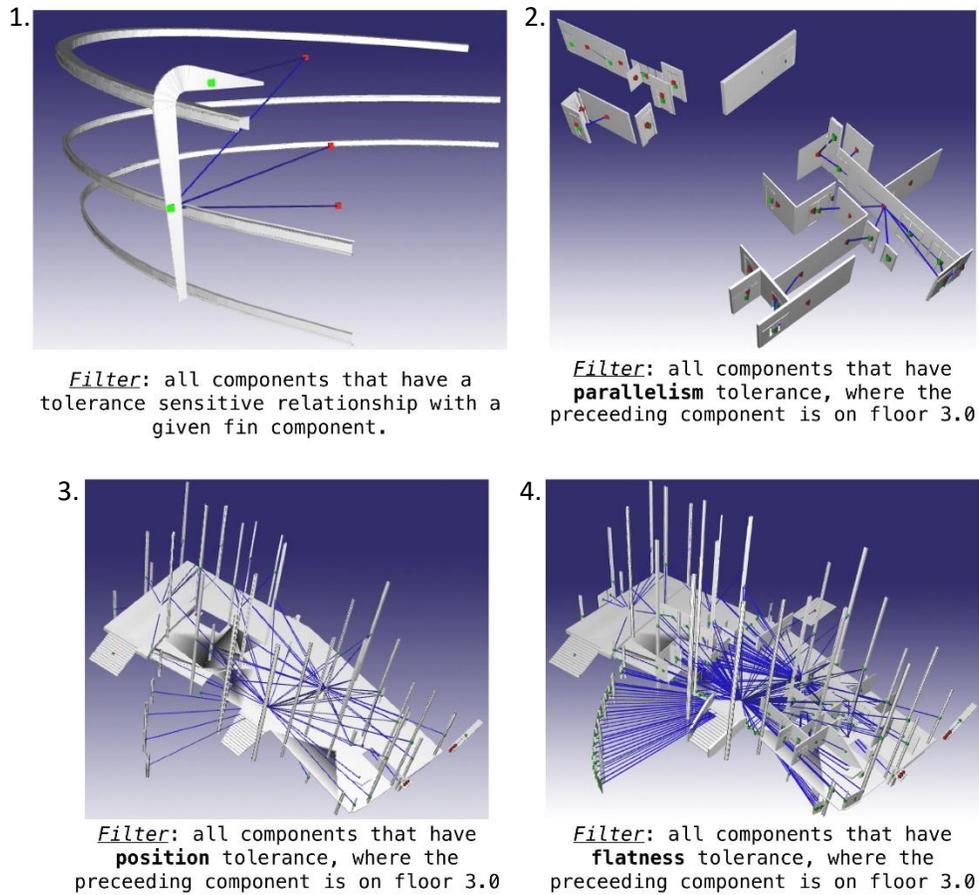
726 Figure 14 illustrates the fragments of the BIM that correspond to each cell in the matrix that is assigned a
 727 tolerance sensitive type. In total, 10387 tolerance sensitive relations were inferred: 7063 flatness; 2173
 728 position; 189 perpendicular; 962 parallel.



729

730 **Figure 14: Filtering Oastler components that have a tolerance sensitive relation based on class type, as**
 731 **specified in the employed interdependency matrix (label format is: <preceding component> –**
 732 **<succeeding component>).**

733 Having inferred the tolerance sensitive relations and added them to the BIM, a range of rich queries (or
 734 "filters") can be applied. Figure 15 illustrates four such examples: (1) finding components that have a
 735 tolerance sensitive relationship with a given specific component (e.g., the illustrated fin). (2-4) finding pairs
 736 of components that have a tolerance sensitive relation of a specific type (parallelism, position, flatness)
 737 where the preceding component is on a given building story (i.e., floor 3.0 in the example).

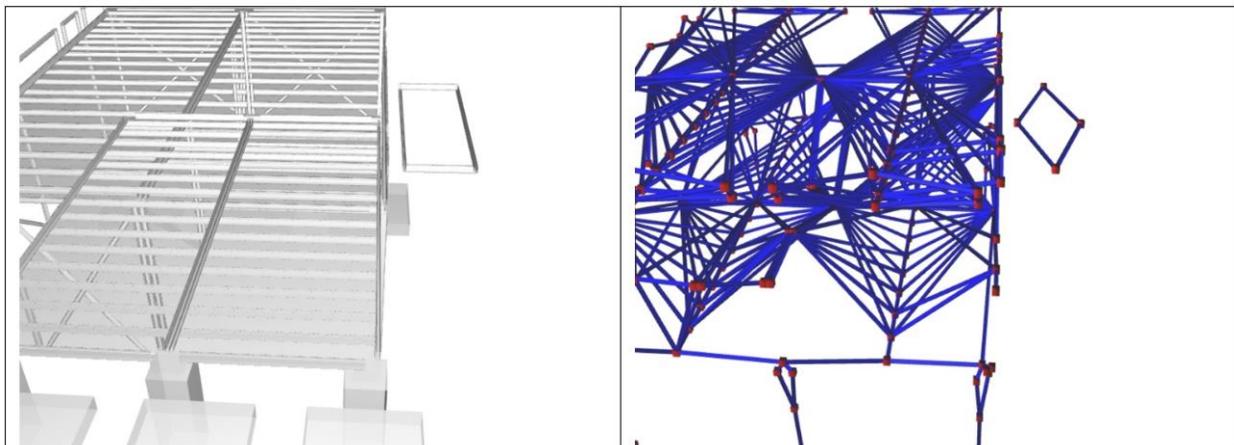


738

739

Figure 15: Four filter examples that demonstrate the versatility of ToleranceDM.

740 In both the "Simple Modular" and "Oastler", using the mesh bounding boxes resulted in some components
 741 not having contact with any other component. In such cases, the contact graph is not complete, and thus
 742 not all components are reachable from every other component through the contact graph, as illustrated in
 743 Figure 16. Methods such as Delaunay triangulation can be used to find minimum distances between
 744 components such that the contact graph is complete.



745

746

Figure 16: Example illustrating "float freely" component groups.

747 The computational runtimes for three derivation and analysis tasks are presented in Table 5. The longest
 748 task is parsing the BIM to derive the mesh geometries. Inferring all 13,000 contact relations of the Oastler
 749 completed within 1 minute, which is fast enough to be practical for construction planning. Column 3 entries
 750 indicate runtimes for deductive reasoning, i.e., compute the consequences of inference rules. Column 4
 751 entries indicate runtimes for abductive reasoning, i.e., check compatibility of these consequences with
 752 domain constraints and amend inference rules if necessary. The validity check when applied to the (non-
 753 trivial) buffered bounding box case of the Oastler finishes within 21 seconds and is again fast enough to
 754 scale to large BIMs.

755 *Table 5: Computational runtimes for BIM augmentation tasks performed on the demonstration BIMs.*

BIM	Time taken to parse IFC geometries into 3D meshes (seconds, 2dp)	Time taken to infer contact relations (seconds, 2dp)	Time taken to check contact validity with buffered bounding boxes (seconds, 2dp)
Simple Modular	3.00 s	0.38 s	0.03 s
Oastler	83.00 s	57.65 s	20.14 s

756

757 6.0 Conclusions and Future Work

758 The specification, control and overall management of tolerances is a vital component to project success in
 759 the construction industry. This is manifested in both the design and construction stages of a project:

- 760 • As BIMs undergo stages of refinement in the design process, objects’ geometric and functional
 761 features are described by increasing levels of development (LODs). LODs define the confidence
 762 level of a BIM, i.e., how well a model reflects the design intent. Any deviation should be subject
 763 to a tolerance check in order to validate or abstract the results of uncertain and indefinite
 764 information contained in BIMs. A holistic approach to manage and document tolerances is
 765 therefore highly valuable (yet currently elusive) to explicate requirements about BIMs with specific
 766 LODs, as it provides a common understanding of how much a BIM can be trusted.
- 767 • During the construction stage, dimensional variability associated with the form, position and
 768 orientation of components is unavoidable. If not properly understood, controlled or managed, this
 769 variability can propagate to cause expensive and time-consuming tolerance issues (predominately
 770 between the interfaces of components). Despite previous attempts to develop and address a holistic
 771 tolerance management framework, existing works to date have not been organized into a practical
 772 and automated process.

773 This paper is a novel contribution that bridges these gaps by developing a domain model for tolerance
 774 management (ToleranceDM) that can be universally applied across a wide range of projects. This domain
 775 model takes inputs in the form of a dependency structure matrix, which outlines the tolerance sensitive
 776 relations between components and parts of an overall construction assembly. Using spatial reasoning and
 777 an inference engine, tolerance sensitive relations are automatically identified, parsed, and enriched on the
 778 input BIM. As illustrated in the results of two case studies, an initial BIM is semantically enriched for
 779 tolerance management-focused visualization and querying. This enrichment is shown to be effective even
 780 when key connection details are not present in an initial BIM (i.e., LOD 300). ToleranceDM is shown to
 781 be effective and practical, through functional demonstration of a small BIM and a larger, more complex
 782 BIM.

783 6.1 Intelligently Inferring Contact Relations

784 As part of future work, a more comprehensive abduction (hypothetical reasoning) framework is being
785 developed to intelligently infer a plausible set of contact relations as a basis for reasoning about tolerance
786 sensitivity. The comprehensive abduction framework that is being developed is formulated as follows.

- 787 • Contact relations between each pair of components are the *abducibles* (candidate *hypotheses*). That
788 is, if there are N components, then there are N^2 component pairs, and because contact is symmetric
789 and reflexive, then there are $N(N-1)/2$ distinct candidate hypotheses.
- 790 • Each *hypothesis* (that some pair of components have contact) must be *justified* by "evidence", i.e.,
791 the geometric information provided in the BIM (primarily distance and relative orientation) and the
792 component class types. For example, in order for a contact relation to be justified, the distance
793 between components must be within a specified threshold, and in some cases component surfaces
794 must be parallel so that they can meet flush when moved together.
- 795 • A *scenario* is a set of hypothesized contact relations. Thus, the size of the scenario space is $O(2^N)$,
796 i.e., exponential in the number of components.
- 797 • A *valid scenario* is one that satisfies all domain constraints, such as no "free floating" components.
- 798 • Scenarios are *ranked* by metrics, such as preferring scenarios that minimize the number of
799 hypotheses.
- 800 • The *abduction task* is to find the highest-ranking valid scenarios.

801 A spatial reasoning extension of ASP is being utilized [51,52] to efficiently prune the search space of valid
802 hypotheses. This is achieved by defining a series of increasingly accurate conditions that are necessary (but
803 not sufficient) for meshes to satisfy distance and orientation constraints. For example, the following spatial
804 constraints are necessary for two meshes to be within a threshold distance D , and each successively
805 increases in computational complexity and accuracy:

- 806 • The intersection of bounding boxes buffered by D .
- 807 • The intersection of component-aligned bounding boxes buffered by distance D .
- 808 • Distance to hyperplane of separation being less than $D/2$.

809 The domain constraint determining contact graph validity is also being refined. In particular, the "free
810 floating" constraint is not sufficient – components need to be *supported* so that they are stable within the
811 assembly. Being supported implies contact, but also involves other component-specific criteria, the
812 evaluation of which may require physics and statics simulators and corresponding qualitative spatial rules,
813 e.g., "a component that has contact with a slab from below is supported by that slab". The revised validity
814 condition is thus that every component is transitively supported by a foundation component.

815 This leads to yet another aspect of future work which is the automated enrichment of BIM class types. In
816 BIM standards such as IFC, certain types of component classes are not defined although they are critical to
817 reasoning about tolerance. For example, a slab may be laid at the base of a design as the foundation,
818 although the class of the component in the BIM is IfcSlab (and no such class as IfcFoundation currently
819 exists). Thus, logical rules are needed to reason about whether a component is a particular subclass, such
820 as foundations.

821 **6.2 Expanding the Tolerance Domain Model**

822 As illustrated in Figure 1, the purpose for the first version of ToleranceDM is to provide a way to
823 semantically enrich BIM with tolerance management concepts. In this paper, we outline how such an
824 enriched BIM could be queried, however future work will expand upon the use cases to explore the
825 following: automated tolerance analysis, automated tolerance synthesis, visualization of project risks

826 related to tolerances, interactive development of tolerance interdependency matrix, and construction
827 progress monitoring while considering tolerances. The developed version of ToleranceDM will enable users
828 to interactively edit the default tolerance interdependency matrix and adjust it to the peculiarities of each
829 project. For progress monitoring, ToleranceDM will be developed further to assess the compliance of
830 installed components with the specified tolerances by comparing as-built data (e.g., a point cloud) with
831 BIM as well as comparing the as-built data over time. This function will be linked with 4D BIM in order
832 to check whether the installed components comply with the specified tolerances when components in
833 critical connections are installed. This is particularly important when considering building movement (i.e.,
834 geometric changes over time as a result of deflection, drying shrinkage, foundation movement). For
835 example, cladding systems should be capable of incorporating deviations of the structural assembly due to
836 its self-weight and other loads applied afterwards as well as deviations of workmanship when installing the
837 cladding system. The developed version of ToleranceDM will assess whether deviations of the structural
838 assembly and cladding system comply with the specified tolerances at the time of installation. Further, the
839 development team will conduct a more comprehensive refinement process through structured interviews
840 with domain experts across the industry. In addition, ToleranceDM will be further scrutinized and tested
841 on several large-scale construction projects.

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Appendix A: Tolerance Interdependency Matrix for Oastler Functional Demonstration

	Foundation		Concrete slabs		Columns			Roof	Staircase		Curtain Wall			Balustrade	Parapets	Fins	Internal Partitions			Stone Cladding	Office Doors		
	Top surface	Top surface	Bottom surface	Top	Middle	Bottom baseplate	Top surface	Top	Bottom	Top adjustable connection	Bottom	Right/left	Bottom	Bottom	Top/bottom adjustable	Top slotted head track	Bottom slotted head track	Right/left	Side slotted bracket	Left/rights vertical jamb	Bottom horizontal jamb	Top horizontal jamb	
	C ₁ ¹	C ₂ ²	C ₃ ²	C ₄ ³	C ₅ ³	C ₆ ³	C ₇ ⁴	C ₈ ⁵	C ₉ ⁵	C ₁₀ ⁶	C ₁₁ ⁶	C ₁₂ ⁶	C ₁₃ ⁷	C ₁₄ ⁷	C ₁₅ ⁸	C ₁₆ ⁹	C ₁₇ ⁹	C ₁₈ ⁹	C ₁₉ ¹⁰	C ₂₀ ¹¹	C ₂₁ ¹²	C ₂₂ ¹²	
C ₁ ¹			F			PO																	
C ₂ ²									PO, F	F		F					F					F	
C ₃ ²	F			PE		PO, F		PO, F		F						F							F
C ₄ ³			PE				PE																
C ₅ ³											PO, PA			PO									
C ₆ ³	PO		PO, F																				
C ₇ ⁴													F										
C ₈ ⁵			PO, F																				
C ₉ ⁵		PO, F																					
C ₁₀ ⁶			F																				
C ₁₁ ⁶		F																					
C ₁₂ ⁶					PA, PO																		
C ₁₃ ⁷																							
C ₁₄ ⁷							F																
C ₁₅ ⁸																							
C ₁₆ ⁹																							
C ₁₇ ⁹																							
C ₁₈ ⁹																					PA		
C ₁₉ ¹⁰																							
C ₂₀ ¹¹																			PA				
C ₂₁ ¹²																							
C ₂₂ ¹²		F																					

F= Flatness tolerance, PA: Parallelism tolerance, PO: Position tolerance, PE: Perpendicularity tolerance.

Red = high risk, orange = med risk, green = low risk.

Appendix B: ToleranceDM Specification in EXPRESS

```
SCHEMA ToleranceDM;

ENTITY TmsRelToleranceSensitiveConnects
  ABSTRACT SUPERTYPE OF(ONEOF(TmsRelSize, TmsRelForm, TmsRelOrientation, TmsRelLocation))
  SUBTYPE OF (IfcRelConnects);
  RelatingElement : IfcProduct;
  Provenance : OPTIONAL TmsProvenanceEnum;
  Risk : OPTIONAL TmsRiskCategory;
  Data : OPTIONAL IfcPropertySet;
END_ENTITY;

ENTITY TmsRelSize
  SUBTYPE OF (TmsRelToleranceSensitiveConnects);
END_ENTITY;

ENTITY TmsRelForm
  SUBTYPE OF (TmsRelToleranceSensitiveConnects);
  Form : TmsFormEnum;
END_ENTITY;

ENTITY TmsRelOrientation
  SUBTYPE OF (TmsRelToleranceSensitiveConnects);
  Orientation : TmsOrientationEnum;
  RelatedElement : OPTIONAL IfcProduct;
  WHERE
    ParallelismHasDatum : Orientation <> TmsOrientationEnum.PARALLELISM OR EXISTS(RelatedElement)
END_ENTITY;

ENTITY TmsRelLocation
  SUBTYPE OF (TmsRelToleranceSensitiveConnects);
  RelatedElement : OPTIONAL IfcProduct;
END_ENTITY;

ENTITY TmsRiskCategory
  SUBTYPE OF (IfcRoot);
  RiskType : TmsRiskTypeEnum;
  Severity : TmsRatingEnum;
  Likelihood : TmsRatingEnum;
END_ENTITY;

TYPE TmsProvenanceEnum = ENUMERATION OF (
  NORMAL,
  SPECIAL,
  SPECIFIC);
END_TYPE;

TYPE TmsRiskTypeEnum = ENUMERATION OF (
  STRUCTURALSAFETY,
  CONSTRUCTABILITY,
  AESTHETIC,
  FUNCTIONALITY);
END_TYPE;

TYPE TmsRatingEnum = ENUMERATION OF (
  LOW,
  MEDIUM,
  HIGH,
  UNSPECIFIED);
END_TYPE;
```

```
TYPE TmsFormEnum = ENUMERATION OF (  
STRAIGHTNESS,  
FLATNESS);  
END_TYPE;
```

```
TYPE TmsOrientationEnum = ENUMERATION OF (  
PERPENDICULARITY,  
PARALLELISM);  
END_TYPE;
```

```
END_SCHEMA;
```